



IQS269A Inductive Sensing Quickstart Guide

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1 Overview

The IQS269A device is capable of inductive sensing in both self and mutual inductance modes, with both these modes requiring the biased configuration for proper operation. Figure 1 and Figure 2 show the channel configuration for the biased self inductance and biased mutual inductance respectively. In self inductance mode a channel uses a single coil for both the excitation and sensing. In the mutual inductance mode each channel has a sensing Rx coil that is mutually coupled to a dedicated excitation Tx coil.

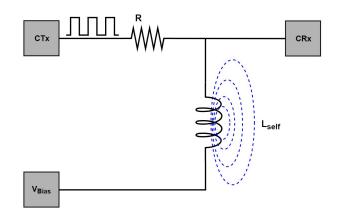


Figure 1: Biased self inductance channel

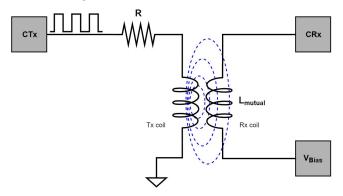


Figure 2: Biased mutual inductance channel

The device has a total of 8 CX pins that can be configured as either excitation pins (CTx) or sensing pins (CRx), with the exception of pin CX1 that is set to the bias voltage in inductive sensing mode. Table 1 shows the possible pin assignments of each of the CX pins.

CX pin	СТх	CRx
CX0	No	Yes
CX1	N/A ⁽¹⁾	N/A ⁽¹⁾
CX2	Yes	Yes
CX3	Yes	Yes
CX4	Yes	Yes
CX5	Yes	Yes
CX6	Yes	Yes
CX7	Yes	Yes

Table 1: IQS269A CX pin assignment in inductive sensing mode



The number of available inductive sensor channels that can be used depends on the inductive sensing mode used. Table 2 shows the available channels for the different sensor modes.

Table 2: IQS269	A sensors	capabilities	for biased	configuration
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Sensing Mode	Available Channels	Number of CTx pins	Number of CRx pins	Bias pin (CX1)	Total pins required
Mutual Inductance (Biased)	6 ⁽²⁾	1	6	Yes	8
Self Inductance (Biased)	3	3	3	Yes	7

For mutual inductance mode with multiple RX sensors, the change in inductance of one sensor by a metal target affects the inductance value of the other RX sensors since all the coils are mutual coupled to the same EM field. Due to the coupling, proximity events over a given sensor should be registered as a relative change in the inductance. For the self inductance mode, the sensors are not coupled and thus a proximity event over a sensor can be registered as the absolute change in inductance.

Design choice between mutual and self mode is primarily dependant on the inductive sensing application. Multiple sensors in the self inductance mode should be used for applications that require absolute readings. Such applications include, encoded event triggers that require a given high-low sequence across the sensors to register a particular event. Multiple sensors in the mutual inductance mode should be used for applications that do not require absolute readings. Such applications include, linear position sliders that indicate the position of a metal target over multiple sensors.

2 Design procedure

- Depending on the inductive sensing application, select either the mutual or the self inductance sensing mode. Refer to Table 2 for the available sensor channels in each mode.
- Determine maximum sensing distance h and design sensor coils with smallest outer diameter D_{out} such that $D_{out} \ge 2h$.
- Select number of turns on each coil such that each coil has the recommended inductance value of at least 0.5 μH. Sensing can be achieved with smaller inductance values, however careful tuning of the tank circuit and device setting is required. A larger inductance value has little significance on the sensing range but provides better noise performance.
- Implement parallel LC tank circuit with resonant frequency f_{res} .

$$f_{res} = \frac{1}{2\pi\sqrt{LC}} \tag{1}$$

For the mutual inductance mode, the LC tank can either be implemented on only the Tx coil or on both the Tx and Rx coils for greater sensitivity.

• Select capacitor value C such that f_{res} and the coil excitation frequency f_{tx} satisfy the response condition

$$f_{res} \ge f_{tx}$$
 (2)

¹CRX1 pin is configured as the bias voltage in inductive sensing mode

 $^{^{\}rm 27}$ channels if CTx signal is provided externally (E.g. PWM from an MCU)

С



3 Self inductance mode

Self inductance mode for the IQS269A requires the biased sensing configuration, where pin CRX1 provides the bias voltage. Each sensor channel has a CTx pin and a corresponding CRx pin.

3.1 Example schematic diagram

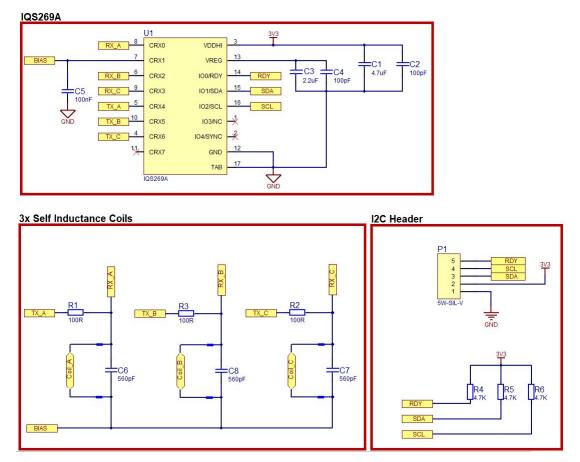


Figure 3: Schematic for 3 self inductance sensors





3.2 Example PCB coil layout

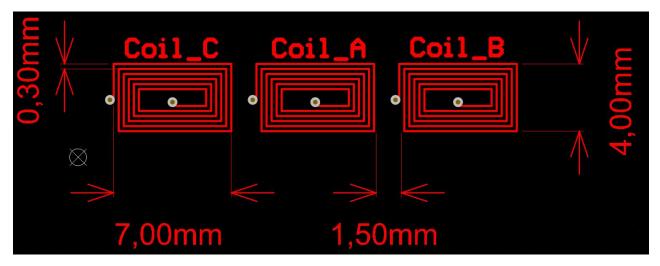


Figure 4: PCB coil dimensions

3.3 LC tank design

The value of parallel capacitor *C* at each of the coils should be selected to satisfy the response condition $f_{res} \ge f_{tx}$. For this example design f_{tx} is set to 16 MHz. Form Equation (1), the response condition is satisfied when $C \le 660 \text{ pF}$.

Due to tolerance in the capacitor value, its good design practice to select a capacitor value that is slightly smaller than the upper limit. This ensures that the response condition is met and the f_{res} is as close as possible to f_{tx} which translates to less signal attenuation. Selecting standard capacitor value of 560 pF $\pm 10\%$ satisfies the response condition.

The design and LC tank tuning parameters of the rectangular PCB coils shown in Figure 4 are given in Table 3.

Shape	Rectangle
Length	7.00 mm
Width	4.00 mm
Number of turns	6
Trace width	0.15 mm
Trace spacing	0.15 mm
Measured inductance (L)	0.14 μΗ
Parallel capacitor (C)	560 pF $\pm 10\%$
fres	18 MHz
f_{tx}	16 MHz

Table 3: Rectangular PCB coil design parameters





3.4 GUI setup

a) Start Streaming and launch user settings window.

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CONFIGURATION TOOL MANAGER	(
CT210A : 431468413034424E05D9FF3! ~	Bar Chart
START STREAMING STOP	800 Legend
Started streaming Started streaming Stopped streaming Power Off Device Connected	600
LOGGING IMPORT H FILE EXPORT H FILE	
SETTINGS	400 -
WRITE CHANGES READ SETTINGS USER SETTINGS	
 Channel select, Power mode & System Settings Report Rates and Timing Global Settings CHO Settings 	200 -

b) Enable CH0, CH1 and CH2

Channel Select	Channel Select (Enable)
Power Mode	
System Settings	🔽 СН0 🗹 СН1 🔽 СН2 🗌 СН3 🗌 СН4 🗌 СН5 🗌 СН6 🗌 СН7
Filter Settings	
Slider Settings	Auto Perced Enable Halt Time
Capacitance Measure	Auto Reseed Enable - Halt Time
Reference Channel Settings	
ATI Settings	✓ CH0 ✓ CH1 ✓ CH2 ✓ CH3 ✓ CH4 ✓ CH5 ✓ CH6 ✓ CH7
Advanced Settings	
CH0 Settings	LTA (reference) halt time (prox/touch time-out)
CH1 Settings	
CH2 Settings	32768 ms
CH3 Settings	52/08 ms

c) Set MCU FOSC to 16 MHz

Channel Select	
Power Mode	Main MCU Oscillator
System Settings	● 16 MHz ○ 4 MHz
Filter Settings	
Slider Settings	Event Mask
Capacitance Measure	
Reference Channel Settings	Proximity Event Mask
ATI Settings	Touch Event Mask
Advanced Settings	
CH0 Settings	DeepTouch Event Mask
CH1 Settings	Gesture Event Mask
CH2 Settings	Reference Channel Event Mask





d) Set f_{tx} to 16 MHz

Channel Select	
Power Mode	
System Settings	If Event Mode - Streaming comms in NP Mode
Filter Settings	
Slider Settings	Global Internal Capacitor Select - requires enable per channel 0.5pF
Capacitance Measure	0 1.5pF
Reference Channel Settings	Excitation signal (Tx) frequency divider
ATI Settings	I FOSC
Advanced Settings	○ FOSC/2 ○ FOSC/4
CH0 Settings	O FOSC/4
CH1 Settings	Reference channel reseed level
CH2 Settings	No Event

e) Configure CH0



f) Configure CH1

Channel Select Sensor Mode: Image: Channel Select Power Mode Sensor Mode: Image: Channel Selection System Settings Mutual Inductance(External) * Inverse Logic Direction Filter Settings CRx Selection Selection	🖉 Settings		
Power Mode Filles Mode System Settings Mutual Inductance(External) * Filter Settings CRx Selection	Channel Select		
Filter Settings	Power Mode		Enable dual direction thresholds
CRy Selection	System Settings	Mutual Inductance(External) Y	Inverse Logic Direction
Slider Settings	Filter Settings	CBy Selection	
	Slider Settings		
Capacitance Measure	Capacitance Measure	✓ 0 □ 1 □ 2 □ 3 □ 4 □ 5 □ 6 □ 7	
Reference Channel Settings	Reference Channel Settings		
ATI Settings CTX Selection (Select all in Surface Sensor Mode)	ATI Settings	Cix Selection (Select all in Surface Sensor Mode)	
Advanced Settings 0 1 1 2 3 🗹 4 5 6 7	Advanced Settings	0 1 2 3 4 5 6 7	
CH0 Settings	CH0 Settings		
CH1 Settings ATI Base Conversion Frequency (Oscillator: 16MHz/4MHz	CH1 Settings		
CH2 Settings ATI Target 75 4MHz/1MHz 0 100 0 2MHz/500kHz	CH2 Settings	All larget	

g) Configure CH2

🗳 Settings		
Channel Select		
Power Mode	Sensor Mode:	Enable dual direction thresholds
System Settings	Mutual Inductance(External) 🎽	Inverse Logic Direction
Filter Settings	CPu Calastian	
Slider Settings	<u>CRx Selection</u>	
Capacitance Measure	0 1 2 3 4 5 6 7	
Reference Channel Settings		
ATI Settings	CTx Selection (Select all in Surface Sensor Mode)	
Advanced Settings	0 1 2 3 4 7 5 6 7	
CH0 Settings		
CH1 Settings		ATI Base Conversion Frequency (Oscillator: 16MHz/4MHz)
CH2 Settings	ATI Target	 75





h) Write changes to devices

CH7 Settings	Deep Threshold ATI Target*Threshold/256	10 🗢	ATI Target*Threshold/256	8 = 16 coun
	· ·			
		26 🗢 52 counts	Hysteresis	4
	Auto ATI Mode Disabled Partial Semi Partial • Full		Coarse Multiplier	
	Compensation	0 🗢	Fine Multiplier	0

i) Acknowledge reset and redo ATI.

	IQS269
ACK RESET SOFT RESET ENTER EVENT MODE	\sim \downarrow \times
Bar Chart	- ü ×
Bar Chart	
600	
400	

j) Expected streaming data.



С



4 Mutual inductance mode

Mutual inductance for the IQS269A requires the biased sensing configuration. In inductance mode the device automatically enables pin CX1 as the bias point.

4.1 Schematic diagram

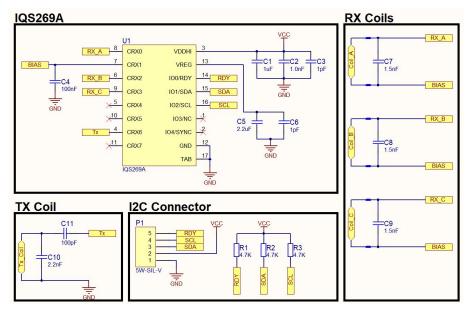


Figure 5: Mutual inductance sensing schematic diagram

4.2 PCB outline

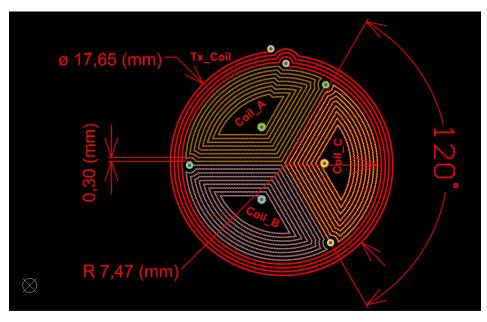


Figure 6: Mutual inductance PCB coil layout



4.3 LC tank design

The same procedure as given in Section 3.3 is followed for calculating the parallel tank capacitor. The *C* value is chosen such that response condition $f_{res} \ge f_{tx}$ is satisfied. The design and LC tank tuning parameters for the Tx and Rx PCB coils are given in Table 4 and Table 5 respectively.

Table 4: Tx circular shaped PCB coil design parameters

Shape	Circle
Diameter	17.65 mm
Number of turns	4
Trace width	0.15 mm
Trace spacing	0.15 mm
Measured inductance (L)	0.61 µH
Parallel capacitor (C)	$2.2\mathrm{nF}\pm10\%$
fres	4.3 MHz
f_{tx}	4 MHz

Table 5: Rx arc shaped PCB coil design parameters

Shape	Arc
Angle	120°
Radius	7.47 mm
Number of turns	9
Trace width	0.15 mm
Trace spacing	0.15 mm
Measured inductance (L)	0.72 μΗ
Parallel capacitor (C)	$1.5\mathrm{nF}\pm10\%$
fres	4.8 MHz
f_{tx}	4 MHz





4.4 GUI setup

a) Start Streaming and launch user settings window.

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Visit Azoteq.com Reset Layout About	
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CONFIGURATION TOOL MANAGER	(
CT210A : 431468413034424E05D9FF3! ~	Bar Chart
START STOP STREAMING STOP	800 - Legend Counts
Started streaming Settings read from device Stopped streaming Power Off Device Connected	600
LOGGING IMPORT H FILE EXPORT H FILE	
SETTINGS	400
WRITE CHANGES READ SETTINGS USER SETTINGS Channel select, Power mode & System Settings Report Rates and Timing	200
 Global Settings CH0 Settings 	

b) Enable CH0, CH1 and CH2

Channel Select	Channel Select (Enable)
Power Mode	
System Settings	🗹 СН0 🗹 СН1 🗹 СН2 🗌 СН3 🗌 СН4 🗌 СН5 🗌 СН6 🗌 СН7
Filter Settings	
Slider Settings	Auto Reseed Enable - Halt Time
Capacitance Measure	Auto Reseed Enable - Hait Time
Reference Channel Settings	
ATI Settings	✓ СН0 ✓ СН1 ✓ СН2 ✓ СН3 ✓ СН4 ✓ СН5 ✓ СН6 ✓ СН7
Advanced Settings	
CH0 Settings	LTA (reference) halt time (prox/touch time-out)
CH1 Settings	64 •
CH2 Settings	32768 ms
CH3 Settings	32700 ms

c) Set MCU FOSC to 16 MHz

Channel Select	
Power Mode	Main MCU Oscillator
System Settings	● 16 MHz
Filter Settings	
Slider Settings	Event Mask
Capacitance Measure	
Reference Channel Settings	Proximity Event Mask
ATI Settings	Touch Event Mask
Advanced Settings	
CH0 Settings	DeepTouch Event Mask
CH1 Settings	Gesture Event Mask
CH2 Settings	Reference Channel Event Mask





d) Set f_{tx} to 4 MHz

Channel Select			
Power Mode			
System Settings	If Event Mode - Streaming comms in NP Mode		
Filter Settings	Global Internal Capacitor Select - requires enable per channel		
Slider Settings	0.5pF		
Capacitance Measure	○ 1.5pF		
eference Channel Settings	Excitation signal (Tx) frequency divider		
ATI Settings	O FOSC O FOSC/2		
Advanced Settings	FOSC/4		
CH0 Settings	O FOSC/8		
CH1 Settings	Reference channel reseed level		
CH2 Settings	No Event In Prox		

e) Configure CH0



f) Configure CH1

Channel Select		
Power Mode	Sensor Mode:	Enable dual direction thresholds
System Settings	Mutual Inductance(External) 🎽	Inverse Logic Direction
Filter Settings	CRx Selection	
Slider Settings		
Capacitance Measure	0 1 2 3 4 5 6 7	
Reference Channel Settings	(The Calendarian (Calendarian Constant Constant)	
ATI Settings	CTx Selection (Select all in Surface Sensor Mode)	
Advanced Settings	0 1 2 3 4 5 7 6 7	
CH0 Settings		
CH1 Settings		ATI Base Conversion Frequency (Oscillator: 16MHz/4MHz) 75
CH2 Settings	ATI Target	 75 4MHz/1MHz 100 2MHz/500kHz

g) Configure CH2

Channel Select			
Power Mode	Sensor Mode:		Enable dual direction thresholds
System Settings	Mutual Inductance(External) 👻		Inverse Logic Direction
Filter Settings	CB- Calastian		
Slider Settings	CRx Selection		
Capacitance Measure	0 1 2 3 4 5 6 7		
Reference Channel Settings			
ATI Settings	CTx Selection (Select all in Surface Sensor Mode)		
Advanced Settings	0 1 2 3 4 5 9 6 7		
CH0 Settings			
CH1 Settings			ATI Base Conversion Frequency (Oscillator: 16MHz/4MHz)
CH2 Settings	ATI Target	16	 ○ 75 ○ 4MHz/1MHz ● 100 ● 2MHz/500kHz





h) Write changes to devices

CH6 Settings	Prox Threshold	10	Touch Threshold	
CH7 Settings		10 🗢 10 counts	ATI Target*Threshold/256	8 16 cou
	Deep Threshold ATI Target*Threshold/250	5 26 🗢	Hysteresis	= 4
	Auto ATI Mode Disabled Partial Semi Partial Full		Coarse Multiplier	
	Compensation		Fine Multiplier	
	WRITE CHANGE	0 🗢	s	0
		ges Made		

i) Acknowledge reset and redo ATI.

	IQS269
ACK RESET SOFT RESET ENTER EVENT MODE	\sim \downarrow \times
Bar Chart	- ü ×
Bar Chart	
600	
400	

j) Expected streaming data.







5 Design considerations

5.1 Series resistor vs parallel LC tank

It is always recommended to use the parallel LC tank circuit at the excitation coil. However, a series resistor can help in reducing the amount of EM emissions while still providing a sufficient sensing signal. This is helpful in cases where EMC compliance required.





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The following patents relate to the device or usage of the device: US 8,395,395; US 8,659,306; US 9,209,803; US 9,360,510; US 9,496,793; US 9,709,614; US 9,948,297; EP 2,351,220; EP 2,559,164; EP 2,748,927; EP 2,846,465; HK 1,157,080; SA 2001/2151; SA 2006/05363; SA 2014/01541; SA 2017/02224;

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